UNITED STATES PATENT AND TRADEMARK OFFICE

APPLICATION NO.	FILING DATE	FIRST NAMED INVENTOR	ATTORNEY DOCKET NO.	CONFIRMATION NO.
10/564,286	01/11/2006	Stefan Carlsson	053339/371970	6990

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EXAMINER
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Please find below and/or attached an Office communication concerning this application or proceeding.

The time period for reply, if any, is set in the attached communication.

	Application No.	Applicant(s)
Office Action Summary	10/564,286	CARLSSON ET AL.
	Examiner	Art Unit
	KENT WANG	2622

-- The MAILING DATE of this communication appears on the cover sheet with the correspondence address --

Period for Reply

A SHORTENED STATUTORY PERIOD FOR REPLY IS SET TO EXPIRE *3* MONTH(S) OR THIRTY (30) DAYS, WHICHEVER IS LONGER, FROM THE MAILING DATE OF THIS COMMUNICATION.
- Extensions of time may be available under the provisions of 37 CFR 1.136(a). In no event, however, may a reply be timely filed after SIX (6) MONTHS from the mailing date of this communication.
- If NO period for reply is specified above, the maximum statutory period will apply and will expire SIX (6) MONTHS from the mailing date of this communication.
- Failure to reply within the set or extended period for reply will, by statute, cause the application to become ABANDONED (35 U.S.C. § 133). Any reply received by the Office later than three months after the mailing date of this communication, even if timely filed, may reduce any earned patent term adjustment. See 37 CFR 1.704(b).

Status

1)☒ Responsive to communication(s) filed on *11 May 2009*.
2a)☒ This action is **FINAL**. 2b)☐ This action is non-final.
3)☐ Since this application is in condition for allowance except for formal matters, prosecution as to the merits is closed in accordance with the practice under *Ex parte Quayle*, 1935 C.D. 11, 453 O.G. 213.

Disposition of Claims

4)☒ Claim(s) *1-8,10-19,21-30 and 32-36* is/are pending in the application.
    4a) Of the above claim(s) _____ is/are withdrawn from consideration.
5)☐ Claim(s) _____ is/are allowed.
6)☒ Claim(s) *1-8, 10-19, 21-30 and 32-36* is/are rejected.
7)☐ Claim(s) _____ is/are objected to.
8)☐ Claim(s) _____ are subject to restriction and/or election requirement.

Application Papers

9)☐ The specification is objected to by the Examiner.
10)☐ The drawing(s) filed on _____ is/are: a)☐ accepted or b)☐ objected to by the Examiner.
    Applicant may not request that any objection to the drawing(s) be held in abeyance. See 37 CFR 1.85(a).
    Replacement drawing sheet(s) including the correction is required if the drawing(s) is objected to. See 37 CFR 1.121(d).
11)☐ The oath or declaration is objected to by the Examiner. Note the attached Office Action or form PTO-152.

Priority under 35 U.S.C. § 119

12)☐ Acknowledgment is made of a claim for foreign priority under 35 U.S.C. § 119(a)-(d) or (f).
    a)☐ All b)☐ Some * c)☐ None of:
      1.☐ Certified copies of the priority documents have been received.
      2.☐ Certified copies of the priority documents have been received in Application No. _____.
      3.☐ Copies of the certified copies of the priority documents have been received in this National Stage application from the International Bureau (PCT Rule 17.2(a)).
    * See the attached detailed Office action for a list of the certified copies not received.

Attachment(s)

1)☒ Notice of References Cited (PTO-892)
2)☐ Notice of Draftsperson's Patent Drawing Review (PTO-948)
3)☐ Information Disclosure Statement(s) (PTO/SB/08) Paper No(s)/Mail Date _____.

4)☐ Interview Summary (PTO-413) Paper No(s)/Mail Date. _____.
5)☐ Notice of Informal Patent Application
6)☐ Other: _____.

DETAILED ACTION

Response to Amendment

1. The amendments, filed on 05/11/2009, have been entered and made of record. Claims 9, 20,

   and 31 have been cancelled and claims 1-8, 10-19, 21-30 and 32-36 have been amended.

   Claims 1-8, 10-19, 21-30 and 32-36 are pending.

Response to Arguments

2. Applicant's arguments with respect to claims 1-8, 10-19, 21-30 and 32-36 have been

   considered but are moot in view of the new ground(s) of rejection.

Drawings

3. The drawings were received on 05/11/2009. This drawing which includes Figs 3a, 3b, 4, 5,

   6a and 6b are replacing the original sheets including Figs 3a, 3b, 4, 5, 6a and 6b. These

   drawings are accepted and made of record.

Specification

4. The substitute specification received on 05/11/2009 has been accepted, entered and made of

   record. Therefore, the objection has been withdrawn.

Claim Rejections - 35 USC § 103

5. The text of those sections of Title 35, U.S. Code not included in this action can be found in a

prior Office action.

6. Claims 1-3, 5-8, 10, 14-19, 21, 25-30, 32, and 36 are rejected under 35 U.S.C. § 103(a) as

being unpatentable over Lee (US 6,778,207) in view of Chang (US 7,307,654).

Regarding claim 1, Lee discloses a method for generating a wide image video sequence

(provide piecewise coverage of a panorama with overlapping visual fields) (1:63-66) using a

device having at least two video cameras substantially co-located in a predetermined

relationship to each other such that there will be an overlap (i.e. overlap region 300, Fig 4)

between images (i.e. regions P and Q, Fig 4) from the respective cameras (i.e. three cameras

91, 92, and 93 arranged so that their respective fields of view overlap) (5:8-21 and Fig 2),

said method comprising the step of :

- forming a synthetic image from images of the respective cameras by: (i) identifying

corresponding parts in overlapping parts of the images (as illustrates in Fig 4, two

overlapping regions P and Q overlap in a region 300 as the regions P and Q have

already been warped to a common surface so that features in each image being

identified and coincided) (5:48-6:6) and (ii) determining the relation between the

respective coordinates for the pixels in the individual cameras and in the synthetic

image (the pixel properties of overlapping image regions are blended 220, as the

blending of properties (e.g., R, G, B, and/or intensity) may be achieved by weighted-

averaging the properties of overlapping regions in the merged images, wherein any or

all of the pixel properties may be weight-averaged within the domain and as shown in

Figs 7-9, the application of the transform to Image I2 to yield image region I2', and

the four registration points of the object images 317 and 319 coincide at 321 in the

overlapping region 320) (5:40-6:59).

- synchronously recording video sequences using each of said at least two video

  cameras (three cameras 91, 92, and 93, Fig 2); and

- generating a wide image video sequence by combining said synchronously recorded

  video sequences (an array of fixed digital cameras is mounted on an arrangement to

  provide piecewise coverage of a panorama with overlapping visual fields) (1:63-66).

Lee does not disclose calculating calibration parameters from said relation, said

calculated calibration parameters being unique for the at least two cameras and their current

location as related to the object being recorded. However, Chang discloses (iii) calculating

calibration parameters (compute both internal and external calibration parameters) from said

relation, said calculated calibration parameters being unique for the at least two cameras and

their current location as related to the object being recorded (compute both internal and

external calibration parameters of first camera 14 and second camera 16, as the internal

calibration parameters include but are not limited to the focal length and lens distortion of

each camera and the external calibration parameters include the relative position and

orientation of first and second cameras 14, 16 with respect to one another) (Fig1 and 3-5, and

5:12-53, Chang);

Thus it would have been obvious to one of ordinary skill in the art at the time the

invention was made to include the control module 12 as taught by Chang into Lee's digital

camera, as the suggestion/motivation would have been to enable the controller which is

capable of performing the calibration, analysis, and interpolation computations to derive a

synthesized image, to create synthesized images allows the user to select the most

satisfactory angle to view the scene in order to better ensure that the specific region of

interest at a particular time instance is accessible to the user (3:29-46 and 10:50-64, Chang).

Regarding claim 2, Lee discloses the synchronously recorded video sequences are stored

in a memory means (a processor 110, which having a memory, Fig 1) (5:8-20 and claim

number 8, Lee).

Regarding claim 3, the limitations of claim 1 are taught above, Chang discloses the

synchronously recorded video sequences are used concurrently for generating the wide image

video sequence (at step 130, first camera 14 captures a first subject image of the portion of

subject 52 and planar background 18 positioned within first projection profile 40 and in step

132, which occurs simultaneously with step 130, second camera 16 captures a second subject

image or video of the portion of subject 52 and planar background 18 positioned within

second projection profile 42) (5:54-6:7, Chang).

Regarding claim 5, Lee discloses the wide image video sequence (provide piecewise

coverage of a panorama with overlapping visual fields) (1:63-66) is stored on a memory

means (a processor 110, which having a memory, Fig 1) (5:8-20 and claim number 8, Lee).

Regarding claim 6, the limitations of claim 1 are taught above, Lee does not disclose a

detailed calibration process according to this claim. However, Chang discloses calculating

the calibration (calibration process 102, Fig 3); comprises the following steps:

     a.   starting of calibration process (step 110, Fig 3) (at 110, a predesigned calibration

               pattern 50 is displayed in front of planar background 18, i.e. on front planar

               surface 44) (4:56-5:11, Chang);

b. synchronizing the sequences from each of the at least two cameras (blocks 112

and 116 occur simultaneously, and blocks 114 and 118 occur simultaneously or

near simultaneously) (4:56-5:11, Chang);

c. computing inter-image projective transformations (step 122, Fig 3) (the

correspondence mapping and geometric parameters of planar background 18

determined at 120 are utilized to compute both internal and external calibration

parameters of first camera 14 and second camera 16) (5:32-53, Chang);

d. using the transformations to refer each image to a common reference frame (step

120, Fig 3) (at 120, CPU 30 compares the robust features from the first and

second images to the known characteristics of calibration pattern 50 and performs

a correspondence mapping and the correspondence mapping entails locating each

captured robust characteristic of calibration pattern 50 in first image 14 and noting

the spatial relationship of the captured robust characteristics) (5:12-31, Chang);

e. selecting a real or virtual reference camera such that certain lines on the pitch or

stadium arc substantially horizontal and substantially parallel in the wide image

(step 122, Fig 3) (the overall spatial relationship of first camera 14, second

camera 16, and planar background 18 is used to determine a first coordinate

system with respect to first camera 14 and a second coordinate system with

respect to second camera 16) (5:32-53, Chang);

f. selecting a rectangular region of interest within the wide image (the

correspondence mapping and geometric parameters of planar background 18, Fig

1, as the planar background 18 is determined at 124 based upon the calibration

parameters of each camera) (5:32-53, Chang); and

g. storing the computed values resulting from the calibration process to be used as

the calibration parameters (once the two coordinate systems are derived, the

calibration process is complete and the first subject image or video is recorded by

first camera 14 and transferred to CPU 30 via first video capture device 32) (5:32-

6:7, Chang).

Thus it would have been obvious to one of ordinary skill in the art at the time the

invention was made to include the calibration process as taught by Chang into Lee's device,

as the suggestion/motivation would have been to enable the controller which is capable of

performing the calibration, analysis, and interpolation computations to derive a synthesized

image, to create synthesized images allows the user to select the most satisfactory angle to

view the scene in order to better ensure that the specific region of interest at a particular time

instance is accessible to the user (3:29-46 and 10:50-64, Chang).

Regarding claim 7, the limitations of claims 1 and 6 are taught above, Lee does not

disclose the step of determining lens distortion parameters for each camera and correcting

radial distortion in each image. However, Chang discloses the step of determining lens

distortion parameters for each camera, and correcting radial distortion in each image (adapted

to stretch the synthesized video image on the video display 20 to remove any parallax

distortions) (3:47-67, Chang).

Regarding claim 8, the limitations of claims 1 and 6 are taught above, Chang discloses

the step of selecting non-linear distortion parameters to reduce perspective distortion of the

image (the internal calibration parameters include but are not limited to the focal length and

lens distortion of each camera) (5:32-53, Chang).

Regarding claim 10, the limitations of claim 1 are taught above, Chang discloses the step

b (step 114 and 118, Fig 3) is performed automatically by an algorithm for identification of

corresponding features in concurrent video images and the coordinates for the corresponding

features are input via a computer means (the second image is transferred from second camera

16 to CPU 30 via second video capture device 34. CPU analyzes the second image for the

robust features of calibrated pattern 50) (4:56-5:11 and Fig 3, Chang).

Regarding claim 14, this claim differs from claim 1 only in that the claim 1 is a method

claim whereas claim 14 recites similar features in an apparatus format. Thus the apparatus

claim 9 is analyzed and rejected as previously discussed with respected to claim 1 above.

Regarding claims 15 and 16, these claims recite same limitations as claims 2 and 3,

respectively. Thus they are analyzed and rejected as previously discussed with respect to

claims 2 and 3 above.

Regarding claims 17, 18, 19, and 21, these claims recite same limitations as claims 6, 7,

8, and 10, respectively. Thus they are analyzed and rejected as previously discussed with

respect to claims 6, 7, 8, and 10 above.

Regarding claim 25, this claim recites same limitations as claim 1. Thus it is analyzed

and rejected as previously discussed with respect to claim 1 above.

Regarding claims 26 and 27, these claims recite same limitations as claims 2 and 3,

respectively. Thus they are analyzed and rejected as previously discussed with respect to

claims 2 and 3 above.

Regarding claims 28, 29, 30, and 32, these claims recite same limitations as claims 6, 7, 8, and 10, respectively. Thus they are analyzed and rejected as previously discussed with respect to claims 6, 7, 8, and 10 above.

Regarding claim 36, this claim recites substantially the same limitations as claim 1. Thus it is analyzed and rejected as previously discussed with respect to claim 1 above.

7. Claim 4 is rejected under 35 U.S.C. § 103(a) as being unpatentable over Lee in view of Chang, and further in view of Alonso (US 6,445,293).

Regarding claim 4, the limitations of claim 1 are taught above, Lee and Chang do not disclose the wide image video sequence is transmitted live. However, Alonso discloses the wide image video sequence is transmitted live (the camera system sets the front camera as output image and transmits live video out from this camera) (3:56-65, Alonso).

Thus it would have been obvious to one of ordinary skill in the art at the time the invention was made to include the imaging pickup device as taught by Alonso into Lee and Chang's device, as the suggestion/motivation would have been to guarantee that the camera system will remain in the alarm state in case of an emergency (1:36-39 and 3:41-45, Alonso).

8. Claims 11, 13, 22, 24, 33, and 35 are rejected under 35 U.S.C. § 103(a) as being unpatentable over Lee in view of Chang, and further in view of Matsumoto (US 2003/0071906).

Regarding claim 11, the limitations of claim 1 are taught above, Chang discloses the method according to claim 1 which comprises the following steps:

   a. apply the calculated calibration parameters (at 110, a predesigned calibration pattern 50 is displayed in front of planar background 18, i.e. on front planar surface 44) (4:56-5:11 and step 110, Fig 3, Chang);

c. retrieving one new image from each camera (at 112, first camera 14 captures a
    first image of calibration pattern 50 and at 116, second camera 16 captures a
    second image of calibration pattern 50) (4:56-5:11 and steps 112 and 116, Fig 3,
    Chang);

d. selectively updating the parameters needed to transform intensities in one or more
    of the cameras to eliminate visible seams (correspondence mapping entails
    locating each captured robust characteristic of calibration pattern) (5:12-31 and
    step 120, Fig 3, Chang);

e. selectively adjusting intensities in the images from one or more of the cameras (a
    similar correspondence mapping procedure is completed using the second image
    to determine the geometric parameters of planar background 18 with respect to
    second camera 16) (5:12-31 and step 120, Fig 3, Chang);

f. creating the current seamless, wide image from the current images from each
    camera (map corresponding robust features to determine geometric parameters of
    planar background, since the calibration pattern 50 is a planar surface located
    upon planar background 18, the geometric parameters of planar background with
    respect to first camera 14 are directly computed from the mapped correspondence
    information) (5:12-31 and step 120, Fig 3, Chang); and

g. outputting the image to a display or to a memory storage area (storage device 37,
    Fig 1) (after all calibration parameters are determined, the overall spatial
    relationship of first camera 14, second camera 16, and planar background 18 is
    determined at 124 based upon the calibration parameters of each camera and the

image is to a display or to a memory means) (5:32-53, Chang).

Lee and Chang do not disclose a calibration process is repeated until the end of the

sequence is reached or return to step b until end of generation of the video sequence.

However, Matsumoto disclose a calibration process is repeated until the end of the sequence

is reached (the calibration process is repeated at a predetermined interval until the release

switch (SW1) 126 or the release switch (SW2) 127 is pressed, Figs 7-9) ([0183], Matsumoto)

Thus it would have been obvious to one of ordinary skill in the art at the time the

invention was made to include the calibration process as taught by Chang into Lee's device,

as the suggestion/motivation would have been to enable the controller which is capable of

performing the calibration, analysis, and interpolation computations to derive a synthesized

image, to create synthesized images allows the user to select the most satisfactory angle to

view the scene in order to better ensure that the specific region of interest at a particular time

instance is accessible to the user (3:29-46 and 10:50-64, Chang).

Thus it would have been obvious to one of ordinary skill in the art at the time the

invention was made to include the calibration process as taught by Matsumoto into Lee and

Chang's device, as the suggestion/motivation would have been to enable that the more

accurate correction data can be obtained ([0183], Matsumoto).

Regarding claim 13, the limitations of claims 1 and 11 are taught above, Chang discloses

the new images from each video camera are read from a memory means (storage device 37,

Fig 1) (after all calibration parameters are determined, the overall spatial relationship of first

camera 14, second camera 16, and planar background 18 is determined at 124 based upon the

calibration parameters of each camera and the image is to a display or to a memory means)

(5:32-53, Chang).

Thus it would have been obvious to one of ordinary skill in the art at the time the

invention was made to include the calibration process as taught by Chang into Lee's device,

so as the image data (e.g., video images, image shape and color information) stored in

storage device 37 will be available for use at a later time (6:63-7:20 Chang).

Regarding claims 22 and 24, these claims recite same limitations as claims 11 and 13,

respectively. Thus they are analyzed and rejected as previously discussed with respect to

claims 11 and 13 above.

Regarding claims 33 and 35, these claims recite same limitations as claims 11 and 13,

respectively. Thus they are analyzed and rejected as previously discussed with respect to

claims 11 and 13 above.

9. Claims 12, 23 and 34 are rejected under 35 U.S.C. § 103(a) as being unpatentable over Lee in

view of Chang and Matsumoto, and further in view of Alonso (US 6,445,293).

Regarding claim 12, the limitations of claims 1 and 11 are taught above, Lee and Chang

do not disclose the new images from each camera are read from live sources, each such

source comprising a video camera. However, Alonso discloses the new images from each

camera are read from live sources, each such source comprising a video camera (the camera

system sets the front camera as output image and transmits live video out from this camera)

(3:56-65, Alonso).

Thus it would have been obvious to one of ordinary skill in the art at the time the

invention was made to include the imaging pickup device as taught by Alonso into Aagaard

and Chang's device, so as the camera system will be capable to used by the main system to

increase system versatility and can get any advanced feature shown in the main video system

(3:41-45, Alonso).

Regarding claims 23 and 34, these claims recite same limitations as claim 12. Thus they

are analyzed and rejected as previously discussed with respect to claim 12 above.

Conclusion

10. The prior art made of record and not relied upon is considered pertinent to applicant's

disclosure:

- Ivanov et al. (US 6,911,995) provide a system and method for segmenting a video of

    a scene so that various depths can be detected;

- Peterson (US 7,386,188) provides a methods, systems, and apparatus, including

    computer program products, for merging images of segments of a view to form a

    panoramic image; and

- Peleg et al. (US 6,665,003) provide a new and improved system and method of

    generating and displaying stereoscopic panoramic images.

11. Applicant's amendment necessitated the new ground(s) of rejection presented in this Office

action. Accordingly, **THIS ACTION IS MADE FINAL**. See MPEP § 706.07(a).

Applicant is reminded of the extension of time policy as set forth in 37 CFR 1.136(a).

A shortened statutory period for reply to this final action is set to expire THREE

MONTHS from the mailing date of this action. In the event a first reply is filed within TWO

MONTHS of the mailing date of this final action and the advisory action is not mailed until

after the end of the THREE-MONTH shortened statutory period, then the shortened statutory

period will expire on the date the advisory action is mailed, and any extension fee pursuant to

37 CFR 1.136(a) will be calculated from the mailing date of the advisory action. In no event,

however, will the statutory period for reply expire later than SIX MONTHS from the date of

this final action.

12. Any inquiry concerning this communication or earlier communications from the examiner

should be directed to Kent Wang whose telephone number is 571-270-1703. The examiner

can normally be reached on 8:00 A.M. - 5:30 PM (every other Friday off).

If attempts to reach the examiner by telephone are unsuccessful, the examiner's

supervisor, Sinh Tran can be reached on 571-272-7564. The fax phone number for the

organization where this application or proceeding is assigned is 571-270-8300.

Information regarding the status of an application may be obtained from the Patent

Application Information Retrieval (PAIR) system. Status information for published

applications may be obtained from either Private PAIR or Public PAIR. Status information

for unpublished applications is available through Private PAIR only. For more information

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questions on access to the Private PAIR system, contact the Electronic Business Center

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Service Representative or access to the automated information system, call 800-786-9199 (IN

USA OR CANADA) or 571-272-1000.

/Tuan V Ho/
Primary Examiner, Art Unit 2622
KW
2 July 2009